



## Knowledge Inn (in nature). 21

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### Professional Profile of Dr J(Bob) Balaram

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#### Conspectus:

Balaram, mechanical engineering graduate of IIT, Madras (1980), was awarded Ph.D in 1985 from the American University. Dr Balaram joined JPL (NASA) and was a lead/principal investigator of many Mars exploration missions. Ingenuity helicopter (Hi) of 1.8 Kgs was his brain child. The gestation period was over two decades from conceptualization to the tiny robot (taking the functional form in JPL, Caltech) flying on Mars. It is the first powered flight on another planet in solar system. The NASA's sanction was as a technology demonstration project. Hi's performance in first five flights (IF1 to IF5) excelled and exceeded the expectations of experts. It is a testimony for robustness of hardware and software modules. NASA extended its mission under the head operations demonstration. The unperturbed health and functionality in tact after tenth flight were amazing. This pushed its active participation in Mr. Perseverance Rover Sample Caching Systems science mission. Ingenuity, non-life robotic system, came into being (physical existence) because of a small but passionate team of NASA bagging discoveries and inventions aimed at welfare of progeny of humankind.

Born on September 22, 1952



Tamil Nādu (India)



**Chief engineer  
Ingenuity helicopter,  
JPL, NASA, USA**



13<sup>th</sup> Flight  
<https://youtu.be/bLuZpk9K20Q>

### **Inspiration for J(Bob) Balam in Space missions**

- Balam, a nine year old child, “gobbled up” every thing that broadcasted on the radio about the Apollo moon mission
- Glossy booklets from NASA entranced young Bob
  - This was a response to Bob uncle’s request to U.S. Consulate for information about NASA and space exploration
  - ! Long long before the internet, the U.S. had good outreach
- From then on Balam was fascinated and piqued by the cosmic world and space

	Inspiration stage (Is) to Ingenuity First flight (Iff) Timeline for <b>Dr J (Bob) Balam</b>
1990	✓ Prof IlanKroo of Stanford univ spoke about a ‘mesicopter — a miniature airborne vehicle for applications on Earth’

	<ul style="list-style-type: none"> <li>✓ NASA funded the project under “Innovative Advanced Concepts”</li> <li>✓ <b>From to-do to done</b></li> <li>✓ A seed of thought was sown in the Dr Balamam’s mind to fly an appropriate small vehicle on MARS</li> </ul>
Proposal submitted	To NASA Research Announcement It is in joint collaboration with Stanford Univ & Recruited AeroVironment, a small company in Simi Valley, California
	<ul style="list-style-type: none"> <li>✓ The proposal got favorable reviews</li> <li>- But it was not selected for funding at that time,</li> <li>! It did yield a blade-rotor test under Mars conditions at JPL</li> </ul>
<b>15years</b>	<b>!</b> Idea "sat on a shelf" for 15 years

<b>! Revival</b>	
<b>!</b> Charles Elachi, then the director of JPL, attended a conference	<ul style="list-style-type: none"> <li>☞ University of Pennsylvania presented about the use of drones and helicopters</li> </ul>
<b>?</b> Dr Elachi, asked whether something like that could be used on Mars	
	<ul style="list-style-type: none"> <li>○ A colleague of Balamam's mentioned Bob’s previous work in that area of research</li> </ul>
	<ul style="list-style-type: none"> <li>☞ Elachi asked Dr Balamam to write a new one for the competitive call for Mars 2020 investigation payloads</li> </ul>
<b>! Second Hurdle</b>	
- Helicopter idea was not selected as an instrument	
+ Funded for technology development and risk reduction	

<b>Start of project</b>	
	<ul style="list-style-type: none"> <li>☞ Mimi Aung became Mars Helicopter project manager</li> <li>☞ Team worked on risk reduction</li> </ul>
	<b>! Funding</b>
✓ NASA decided to fund the helicopter for flight as a technology demonstration	
<b>! Landing on MARS</b>	
2021 February 18	Ingenuity arrived on Mars
2021 April 19	It took its first 39-second maiden flight
<p>F1 to F5 : successful technology demonstration flights  F6 to F9: successful Operation demonstration flights  F10 to F13: successful exploration experimental learning (Eel) flights</p> <p><b>Off the Earth, for the Earth, and Beyond</b></p>	

### Appreciation of Ingenuity helicopter (Hi!)

MiMi Aung (Burmese-American) is a project manager at NASA's Jet Propulsion Laboratory (JPL); lead engineer on the Mars Helicopter Ingenuity said

- ! “This morning our dream came true.”
- ! “It is an incredible moment”
- ! This flight (Hi) (extraterrestrial aircraft) is compared to Wright brothers' airplane which was the first flight in 1903 at Kitty Hawk on Mother earth
- ! Beginning of the "pioneer era" of aviation on MARS, the first planet other than earth in our solar system

### Appreciation of Dr J(Bob) Balam

- ! Dr Bob is the inventor of our Mars Helicopter
- ! It is his innovated vision to its fruition (as a chief engineer) through all phases of design, development, fabrication and test

### Open heart with Ingenuity helicopter (Hi!)

Interviewer: Did people thought that the idea of Mars ingenuity was crazy

Balam: “Everyone. All the time.”

- ✓ A postage-sized piece of fabric that covered one of the wings of the Wright brothers' first aircraft was attached to a cable under the solar panel of Ingenuity. Now the cloth is on MARS with Hi and its mother perseverance after a travel for over six months from Earth
- ✓ Ingenuity helps scientists on Earth in three tasks viz. - reach, range and resolution
  - ! to look at hard-to-reach places like steep cliff walls, caverns or other geological structures on Mars
- ✓ Helicopters have a larger range compared to rovers, but with different specific purposes designed for
- ✓ Bob opined before landing that these helicopters basically opens up a whole new dimension of exploring Mars
- ✓ Now that Hi excelled its performance both in technology and operations demonstration phases, higher versions with new features open new doors to aviation scientific exploration along with rovers on MARS and other planets (Moons) in coming decades.
- ✓ More than ten engineers of Indian origin are involved in the mission,

## Expertise of Dr J(Bob) Balaram

- 📖 Precision landing methods for Mars
- 📖 Advanced simulation techniques for planetary a high-fidelity EDL (Entry, Descent and Landing)
  - Adapted& used in **Curiosity and Perseverance** rover missions
- 📖 Machine vision for rover hazard detection, improved methods for rover position determination, rover system re-configuration, and software system architectures for rover development
- 📖 Vision-based sensing to achieve automation of servicing operations
- 📖 Module change-out and assembly
- 📖 Remote Surface Inspection for the Space Station in the area of real-time, vision-based flaw detection of damage caused to the Space Station over its lifetime in orbit
- 📖 Combined EDL-Mobility Analysis Trade Study Tool (CEMAT)
- 📖 SHERPA System
- 📖 Telerobot
  - Technology development Testbed for Mars Rovers, planetary balloon aerobot systems

### Lead of team

- 📖 EDL simulator adapted for use in the Mars Science Laboratory mission.
- 📖 Co-developed a simulator used for planetary rover simulation
- 📖 machine intelligence on the JPL Telerobot Testbed
- 📖 responsible for coordinating multiple robotic manipulators

Principal investigator	Beyond Monte-Carlo - Statistical Verification and Validation of Space Systems for entry, descent and landing	DRDF, JPL.
Principal Investigator May 2004 - July 2008	Sherpa System Mars Base Technology Program	NRA, JPL
Task Lead September 2000- Present	EDL Modeling & Simulation, Mars Technology Development Program,	JPL

Awards to Dr J(Bob) Balaram	
Two	NASA Awards
Eight	New Technology awards
	NASA Group Achievement Award
	It been adopted for use by the upcoming Mars Science Laboratory mission

### Earlier flight projects of Dr J(Bob) Balaram

2011	Mars Science Laboratory
2007	Phoenix Mars Lander

### Academic profile of Dr J(Bob) Balaram

1975-80	B.Tech	Mechanical Engineer	IIT, Madras, India
1982	MS	Computer and System Engineering	America's Rensselaer Polytechnic Institute
	Thesis	Analysis of Boiling Water Nuclear Reactor Stability Margins	
1985	Ph.D	Computer and System Engineering	America's Rensselaer Polytechnic Institute
	Thesis	Suboptimal Control of Nonlinear Systems	

### Research papers of Dr J(Bob) Balaram

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11. J. Balaram, "**Kinematic Observers For Articulated Rovers**," 2000 IEEE Conference on Robotics & Automation, San Francisco, USA, April 2000.
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15. J. Balaram, Jonathan M. Cameron, James W. Cutts and Kerry T. Nock, "**Autonomous Mobility, Navigation, and Control for Venus Aerobots**," I-SAIRAS 97, July 14-15, Tokyo, Japan.
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Small steps for human scientist

Giant leaps in science  
(and for humankind)

[https://youtu.be/oYE3knI\\_\\_5M](https://youtu.be/oYE3knI__5M)

Mars Helicopter Ingenuity's 4K images from 13th flight and full video footage, Sep 11, 2021, 32,565 views by 16<sup>th</sup> Sep, 2021

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